

R&D Opportunities in Linear Collider Tracking

Dan Peterson
Cornell University
LCCOM 19-April-2002

Baseline Detectors

Momentum resolution and implications

Jet track density and implications

Resolution and segmentation in various technology, R&D issues

TPCs

drift chambers / jet chambers

(baseline in Asia, not considered in N.A. or Europe)

new technology gas amplification TPCs

all silicon trackers

Simulation work

Physics Goals, Implications

clean Higgs signal from di-lepton recoil mass
end-point mass spectra in SUSY cascades

$$d(1/P_t) \sim \text{few } 10^{-5} / \text{GeV}$$

jet energies in $W+W^-$ final states (energy flow analysis)

exceptional pattern recognition,
2-track separation

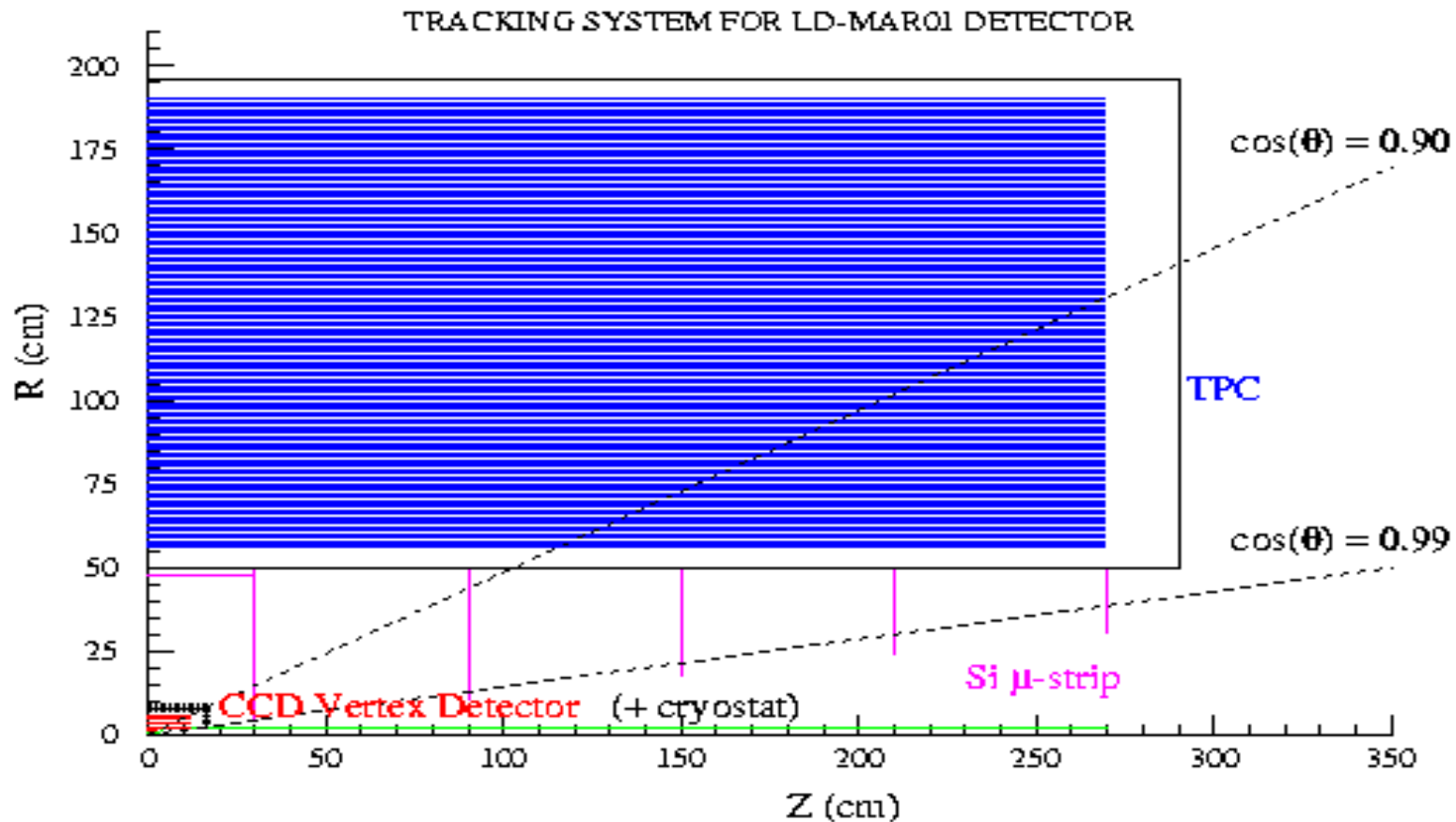
Primary and secondary vertex reconstruction

radially continuous tracking

The large detector baseline design, LD

Goal optimized tracking precision
with large tracking volume

Magnetic field Tesla



North American LD baseline design

Stolen from K. Riles, Chicago Linear Collider Workshop, 7-Jan-2002

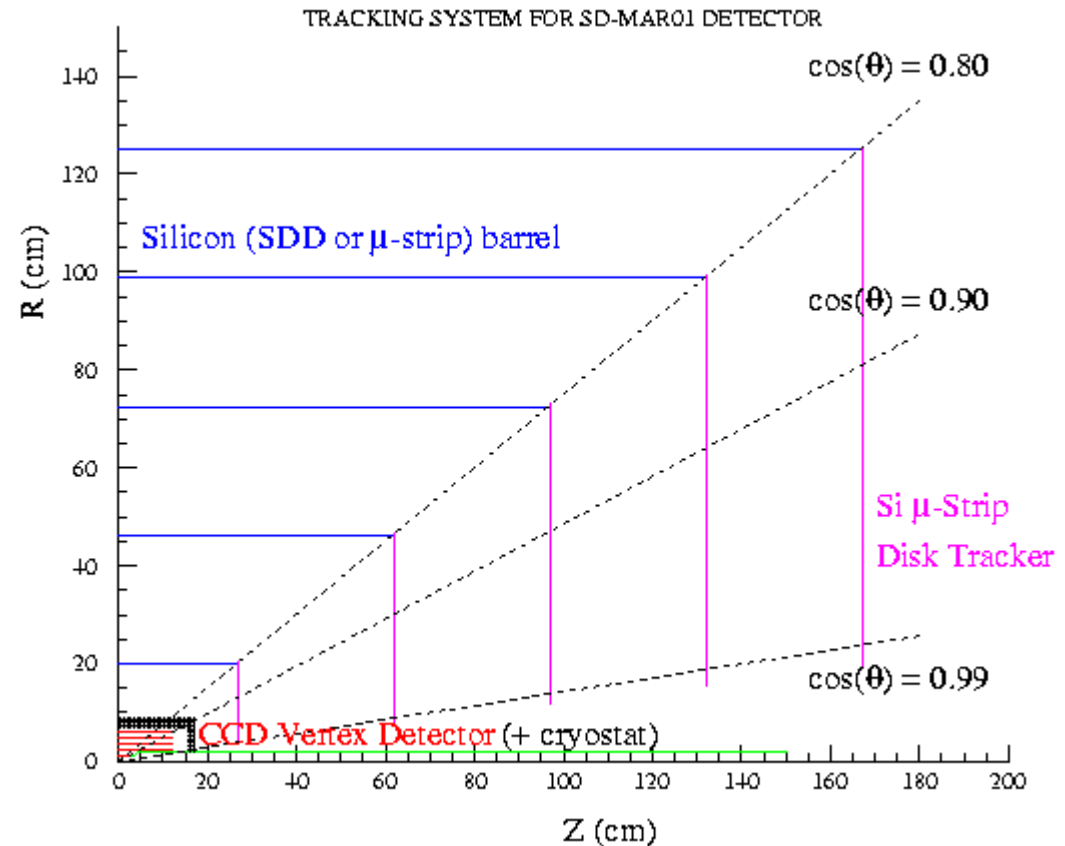
The "silicon detector" baseline design, "D

Energy flow calorimetry - □
Expensive calorimeter - □
Small calorimeter - □

Limit tracking system
Outer radius to 125 cm

Compensate for a
smaller measurement length
with
improved spatial resolution
(although fewer points)
and
higher magnetic field

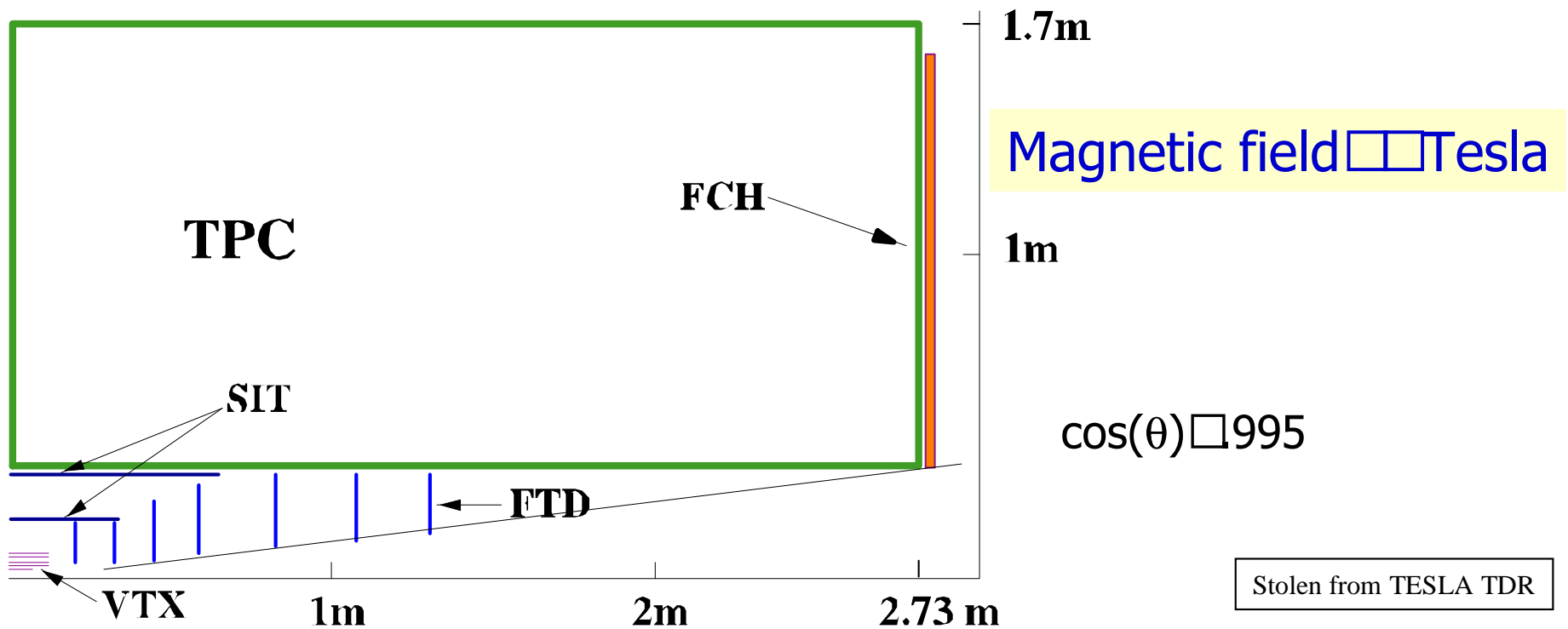
Magnetic field □ 5 Tesla



North American SD baseline design

Stolen from K. Riles, Chicago Linear Collider Workshop, 7-Jan-2002

TESLA tracking system



(differences, wrt North American LD)

1. \approx 1m radius (vs 2 m) , \approx 1 Tesla field (vs \approx 2 Tesla in N.American LD)

SIT is an intermediate tracking device, 2 layers

FCH is a straw tube device, \approx double layers, resolves TESLA bunch (\approx 10 ns)

momentum resolution vs spatial resolution

PHYSICS GOAL

$$\delta(1/p_t) \approx 10^{-5} / \text{GeV}$$

$$\delta(1/R) \approx \sigma/L^2 \left(\frac{20}{(N+1)} \right)^{.5}$$

L is the measured track length

σ is the measurement error

$$R \approx p_t / (.3 \text{ GeV/Tesla } B)$$

Pinning the fit at the B improves resolution by $\sim 2/\sqrt{B}$

$$\delta(1/p_t) \approx \frac{\sigma/L^2 \left(\frac{20}{(N+1)} \right)^{.5}}{(.3 \text{ GeV/Tesla } B)}$$

use measurement length $L \approx 2$ meters (LD)
use $N \approx 100$

$\sigma/B \approx 20$ micron/Tesla,
or

$\sigma \approx 100$ micron resolution, with $B \approx 5$ Tesla

momentum resolution

$\delta(1/p_t)$ goal is difficult with tracking chamber and vertex detector alone.

Try an intermediate silicon device,
R ≈ 5 meter, $\sigma_{r\phi} \approx 10\mu\text{m}$, N ≈ 2

(relaxed) PHYSICS GOAL

$$\delta(1/p_t) \approx 10^{-5} / \text{GeV}$$

(relaxed) magnetic field
≈ Tesla

Tracker ≈ 2m OR , 0.5m R
Vertex detector ≈ 5 layer, 10 μm

tracker 100 μm ----à $\delta(1/p) \approx 5.0 \times 10^{-5} / \text{GeV}$
with VD only, no int. tracker (consistent with previous slide)

tracker 100 μm ----à $\delta(1/p) \approx 1.5 \times 10^{-5} / \text{GeV}$
with VD and int. tracker

tracker 150 μm ----à $\delta(1/p) \approx 1.2 \times 10^{-5} / \text{GeV}$
with VD and int. tracker

Results from
Dan's fast MC

tracker 150 μm ----à $\delta(1/p) \approx 1.0 \times 10^{-5} / \text{GeV}$
with VD and int. tracker (misaligned by 25 μm , 1 mil)

Spatial Resolution

Spatial resolution requirement is aggressive, **100 μm in 5 Tesla field.**

(This result is for a **large chamber** ($r \approx 2$ m) in combination with a **perfect vertex detector** which constrains the fit at the vertex.)

Momentum resolution goal can be met with **150 μm in 1 Tesla field.**

(This result is for LD, a **large chamber** ($r \approx 2$ m) with a **vertex detector** and **intermediate detector**, both $\sigma \approx 10 \mu\text{m}$.)
However, the resolution is sensitive to misalignments .

Large TPCs do not meet either spatial resolution goal. For example,

Aleph $\sigma \approx 100 \mu\text{m}$, STAR $\sigma \approx 500 \mu\text{m}$.

This resolution is partially related to the pad spacing, which comes with the induction readout.
Aleph resolution is $\approx 1/2$ of the pad spacing (≈ 2 mm).
STAR resolution is $\approx 1/3$ of the pad spacing (≈ 2 or 2.9 mm).

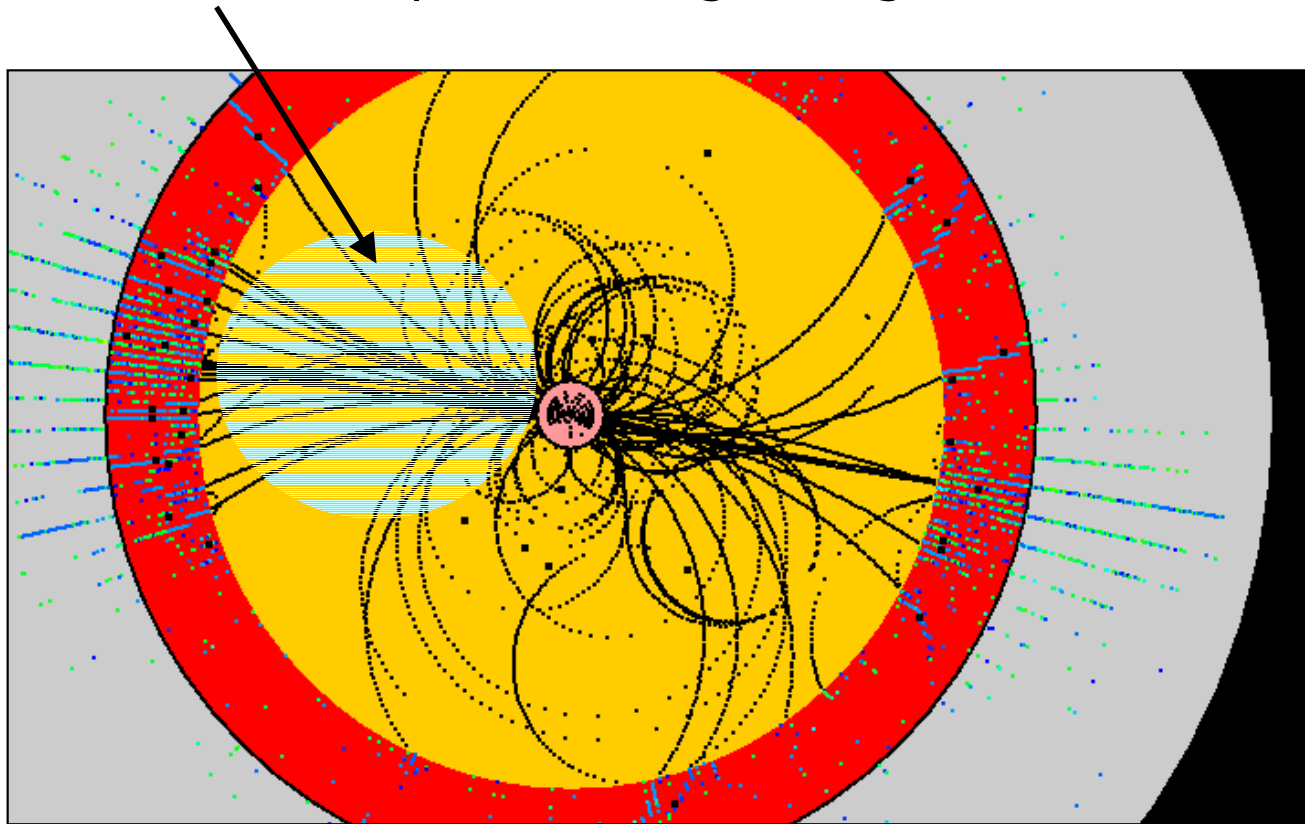
Drift chambers can provide **100 μm** spatial resolution.

Let's see what else is a problem .

Track Density

This typical jet has 19 tracks projected onto an azimuthal angle of 10° .
This is a track density of **19 tracks/ster** (for conical jets) .

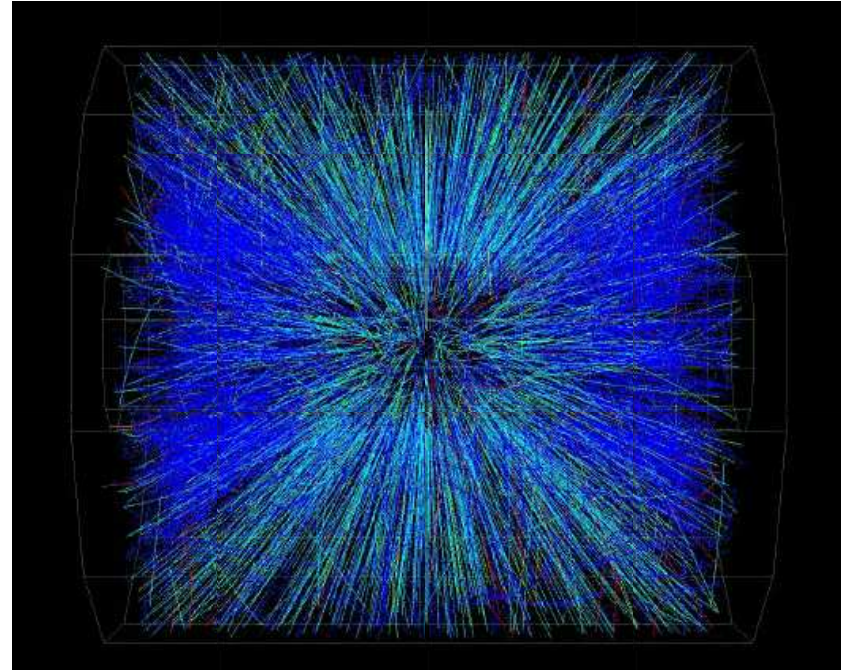
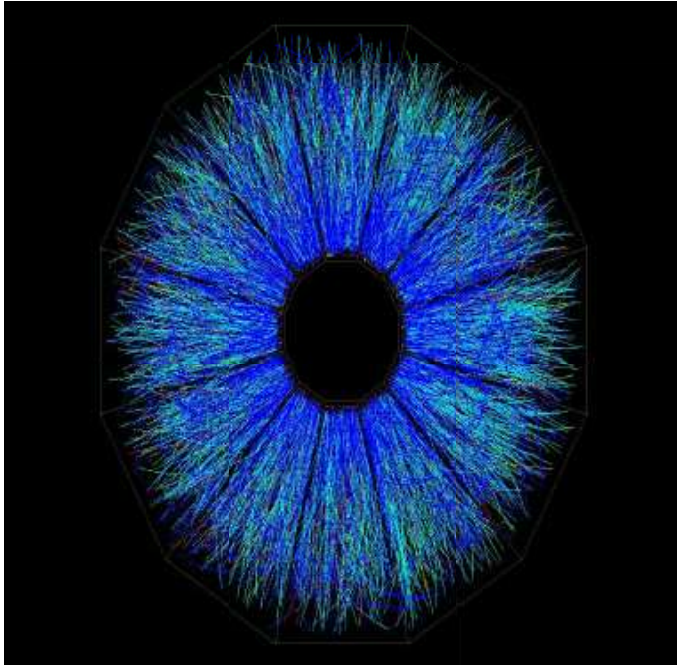
will use **19 tracks/ster** as pattern recognition goal.



JAS 2D LCD Event Display

Stolen from N. Graf, Chicago Linear Collider Workshop, 7- Jan-2002

Compare with the TPC TPC



100 tracks/ster large Yes, that would be 1250 tracks in the event.
STAR observes 1000 to 2000 tracks per event.

this demonstration that a TPC can operate with this track density

No, perfect efficiency is not a goal at STAR look at those panel cracks

Spatial resolution requirement is relaxed $\sigma \approx 500 \mu\text{m}$.

Must do better

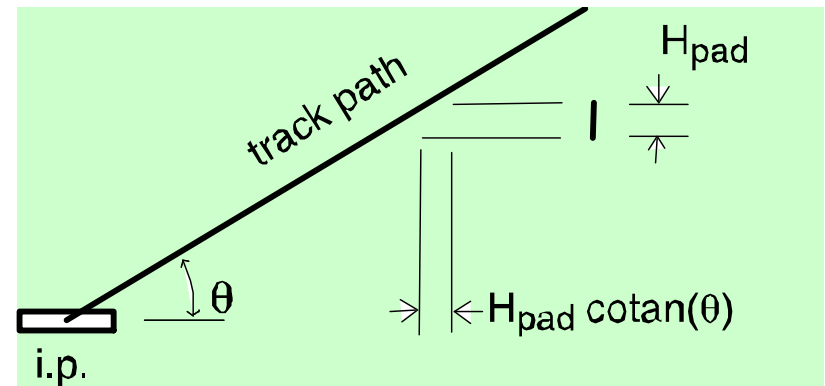
multi-track event in STAR TPC at RHIC

Stolen from J. Thomas, Vienna Conference on Instrumentation, 22-Feb-2001

TPC Segmentation and Occupancy

(induction read-out)

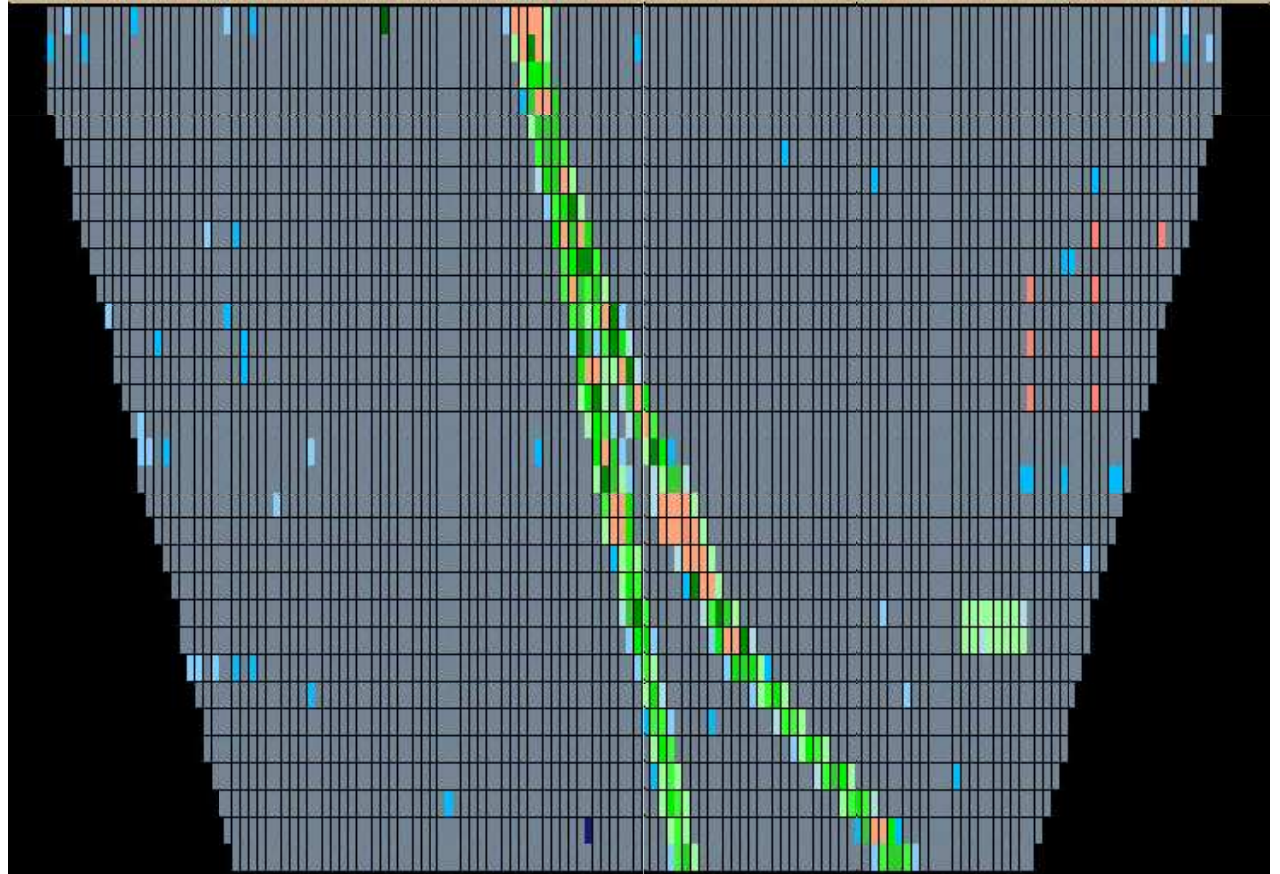
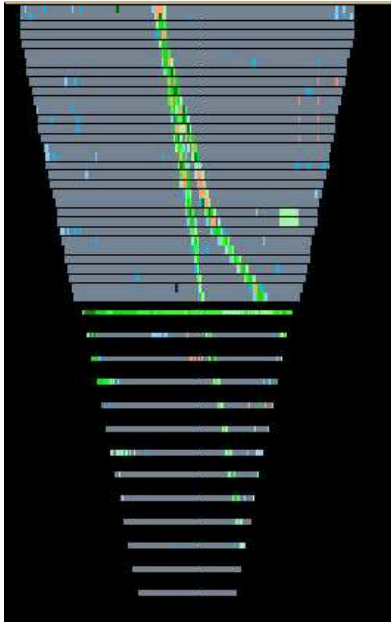
Segmentation is limited by the signal time width, but usually by the travel of the track. Segmentation is typically equal to height of the pad, 10mm or 20 mm



r- ϕ segmentation is limited by the induction read-out. (Gas amplification is due to an avalanche on a wire. Induction signals on pads are read out.)
 STAR signal width, 2-track separation ≈ 25 mm.

Occupancy at $r \approx 50$ cm, with r- ϕ segm. ≈ 2.5 cm, ϕ segm. ≈ 1 cm, segmentation is 1/1000 ster
 occupancy (in jet) is 10^4 , there will be overlapping tracks

Track-track overlap in a TPC



Overlapping tracks are complicated in a TPC.

Pulse height signals on pads can not be resolved beyond the intrinsic segmentation of the device.

Merged signals have **ambiguous position measurement** $\approx \sigma$.

Two tracks in STAR TPC

Stolen from J. Thomas, Vienna Conference on Instrumentation , 22-Feb-2001

TPC projects, TPC (induction) tracker

The (induction) TPC is the baseline, or backup, for advanced readout methods (described later).

Spatial resolution optimization, goal of 150 μm in a large induction TPC.

On feedback suppression gating grids (long gate time at TESLA)

Gas studies aging, velocity (clearing time), quenching, neutron absorption

Alignment

internal alignment and drift path in an inhomogeneous B field

extrapolation to an intermediate tracker hardware & tracking.

(with poorer resolution, system is more dependent on intermediate tracker)

(simulation)

Optimize pattern recognition in an environment of **significant track overlap**.

Drift Chambers

Drift chambers are largely not considered by North America and Europe groups.

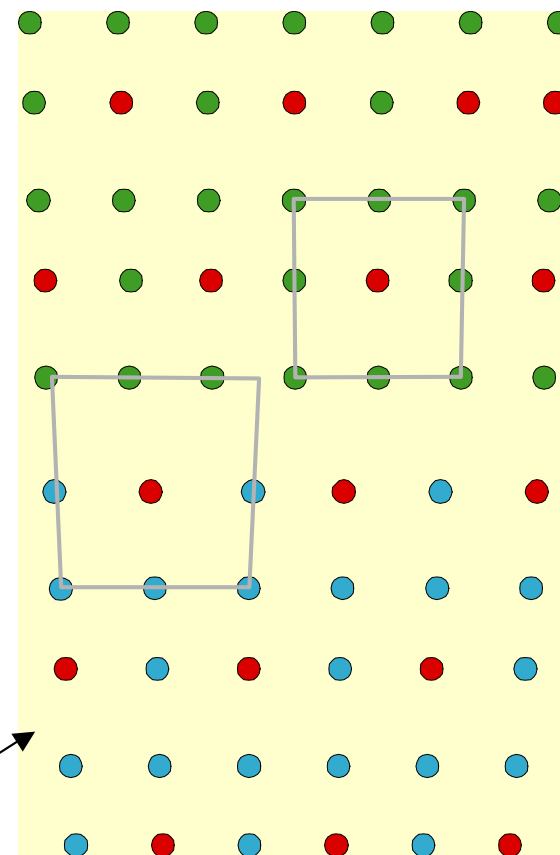
Disadvantages

- poor segmentation (discussion follows)
- wire sag and electro-mechanical instability
- wire tension load on endplate, endplate thickness
- Lorentz angle in a high magnetic field
- current limitation

Drift Chamber (Jet) is the baseline design in Asia.

Advantages

- spatial resolution $\approx 100 \mu\text{m}$ for ≈ 100 of hits (CLEO)
- 2-track separation better than segmentation
(will discuss for 1 cm^2 square cell design)

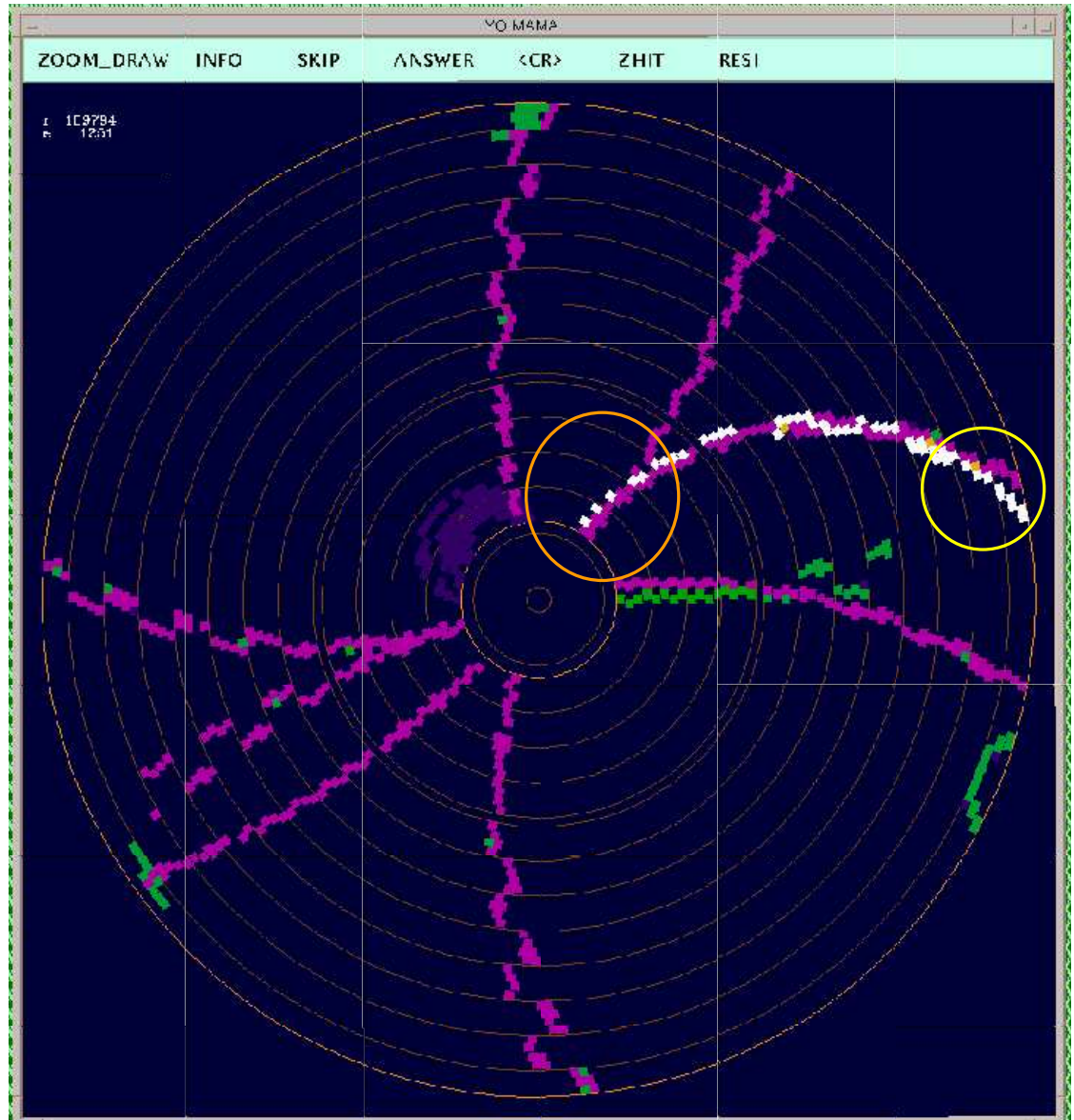


Tracks overlap in a square cell drift chamber

drift chambers,
there is no segmentation.
jet track density ≈ 19 tracks/ 10°
 \approx tracks/radian
 0.1 tracks/cm at $R \approx 50$ cm

Within the orange circle \approx
 \approx tracks within 2 cell widths
(note separation \approx yellow circle).
Observed density \approx
 1.1 tracks/cm
 55 tracks/radian at $R \approx 50$ cm

Tracks are resolved **up to** this
density if sufficient separation
exists elsewhere on the track.



CLEO MC event

Track-track overlap in a square cell drift chamber, resolved

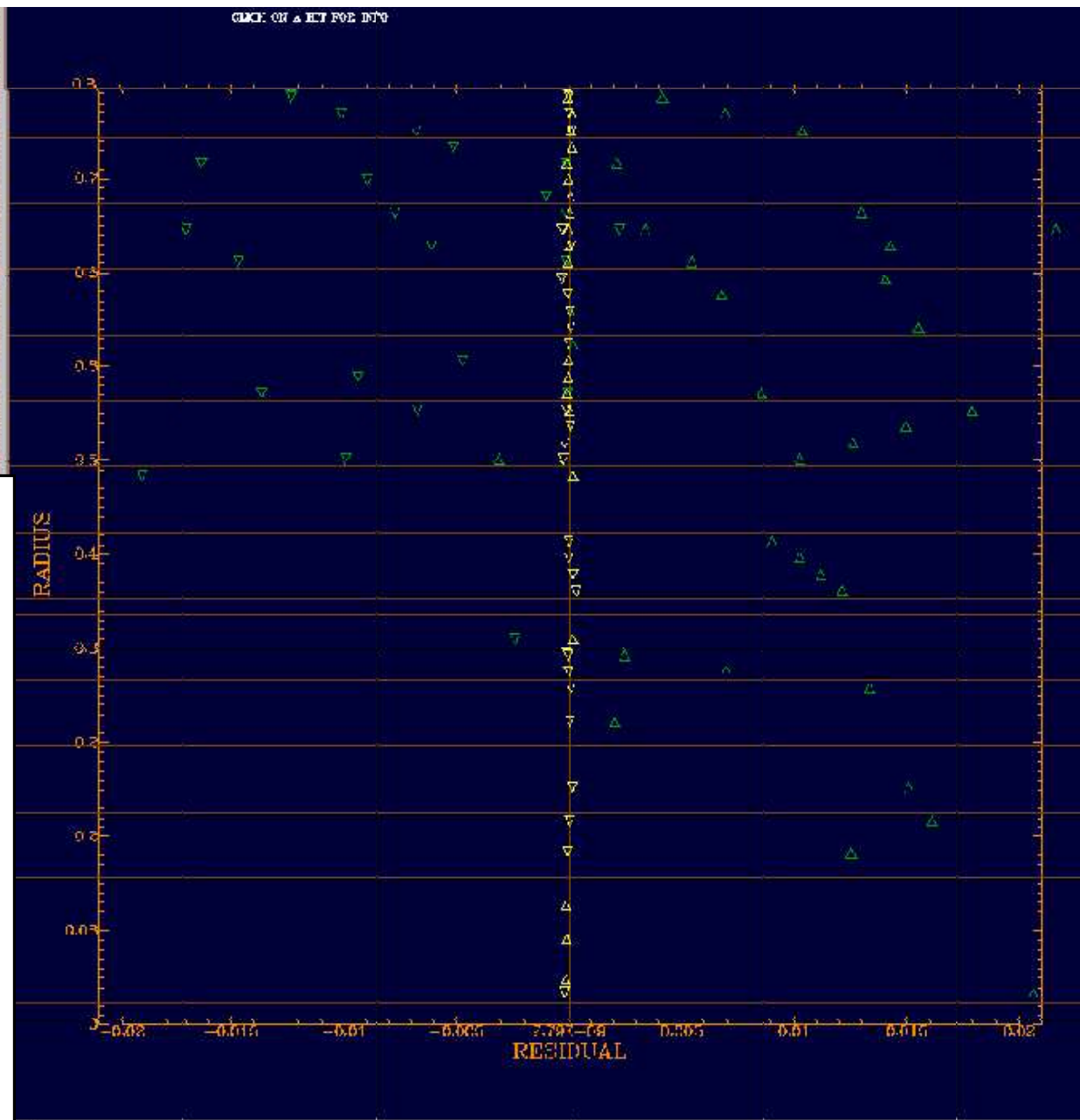
Multi-tracks can be resolved
beyond the
device intrinsic segmentation
because
the time measurement is
valid for one of the tracks.

(some of the hits, all the time)

Method involves extrapolating
in from isolated hit region.

Track separation is better
than intrinsic segmentation.

Applies to Jet Chamber.



Display of hit residuals (horizontal) of
hits on a track (in white on prev. slide) .

Jet Chambers

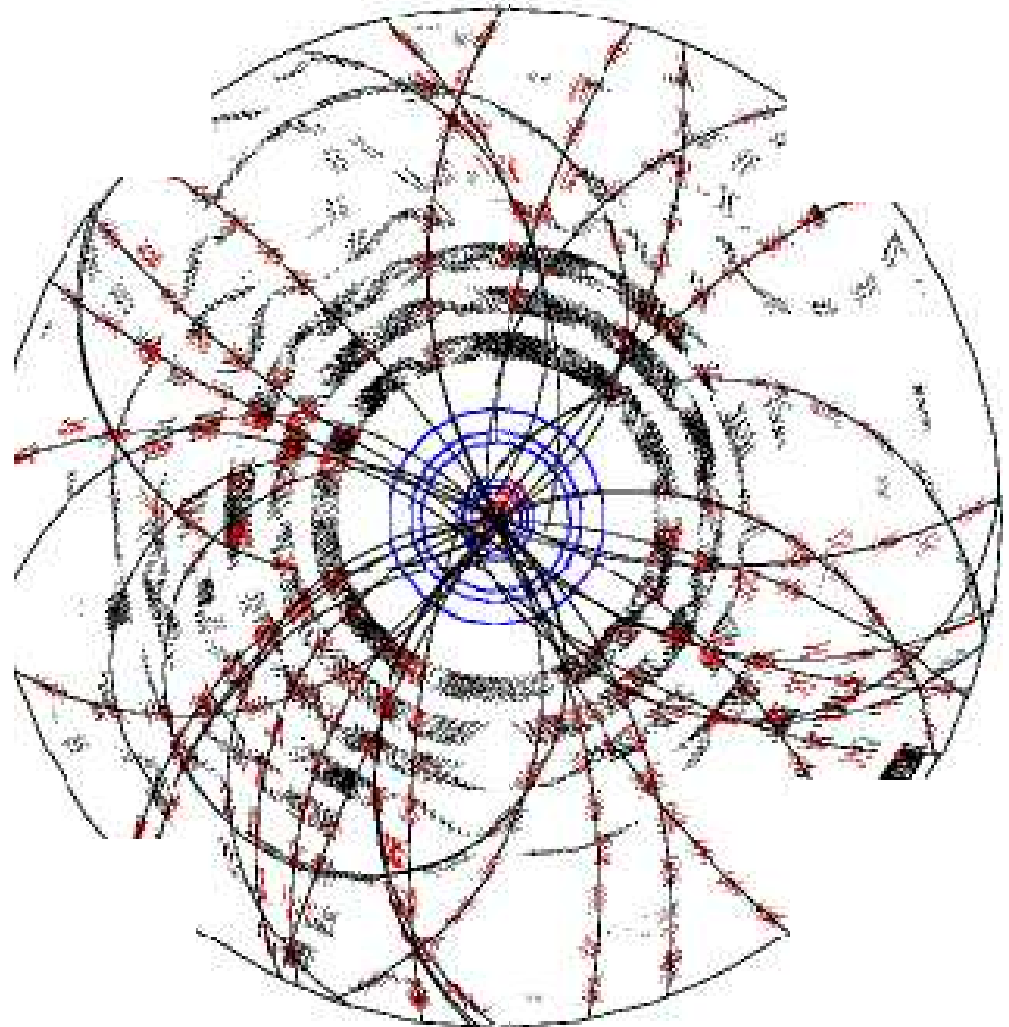
Jet chamber 1mm segmentation
(a 2 mm track separation,
measured in a single layer,
is doubled by the ambiguity)

(while the square cell example
had 1mm segmentation)

Track separation is better
than the 1mm segmentation
as shown for the
case of square cell chamber.

Disadvantage
discontinuous tracking due to
complicated field cage shaping

Expect a track density **limit** of
 $1\text{ track}/\text{mm}$ at $R=50\text{ cm}$
 125 tracks/radian



CD event

CDF Jet Chamber event

Stolen from Y-K Kim, 2001 Lepton Photon Symposium , 23-July-2001

□□□, et Chamber, ongoing/planned (□□□)

□□ will discuss these □□□ results□

Wire sag and electro-mechanical instability
2-track separation
Lorentz angle (and drift velocity)
Spatial resolution

□□ understood□ at □□□□ □

Stable operation of stereo cells
Aluminum wire creep

□□ will not discuss results□ plans in□

Gas gain saturation (affects dE/dx , 2-track separation)
Neutron backgrounds
Optimization of gas mixture

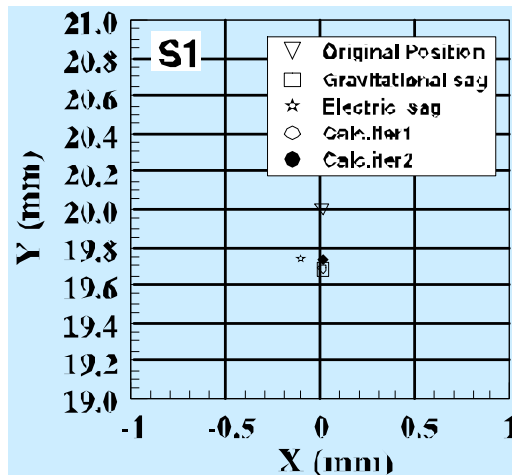
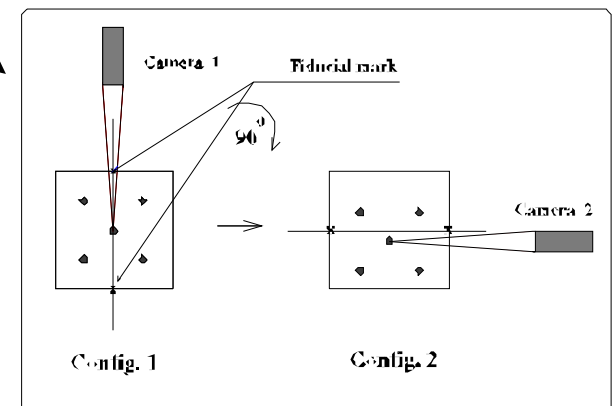
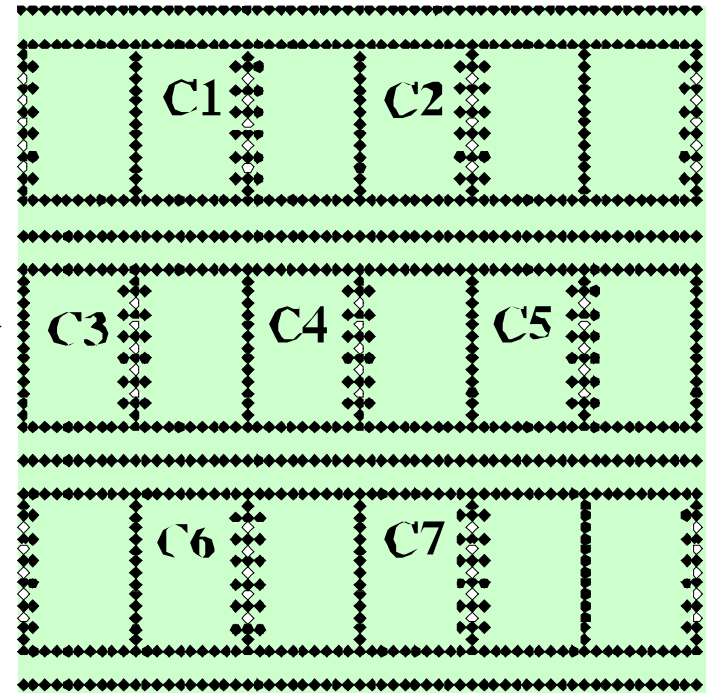
□□ hat should be studied□

Careful study to reconstruction vs track density with full MC.

Get Chamber

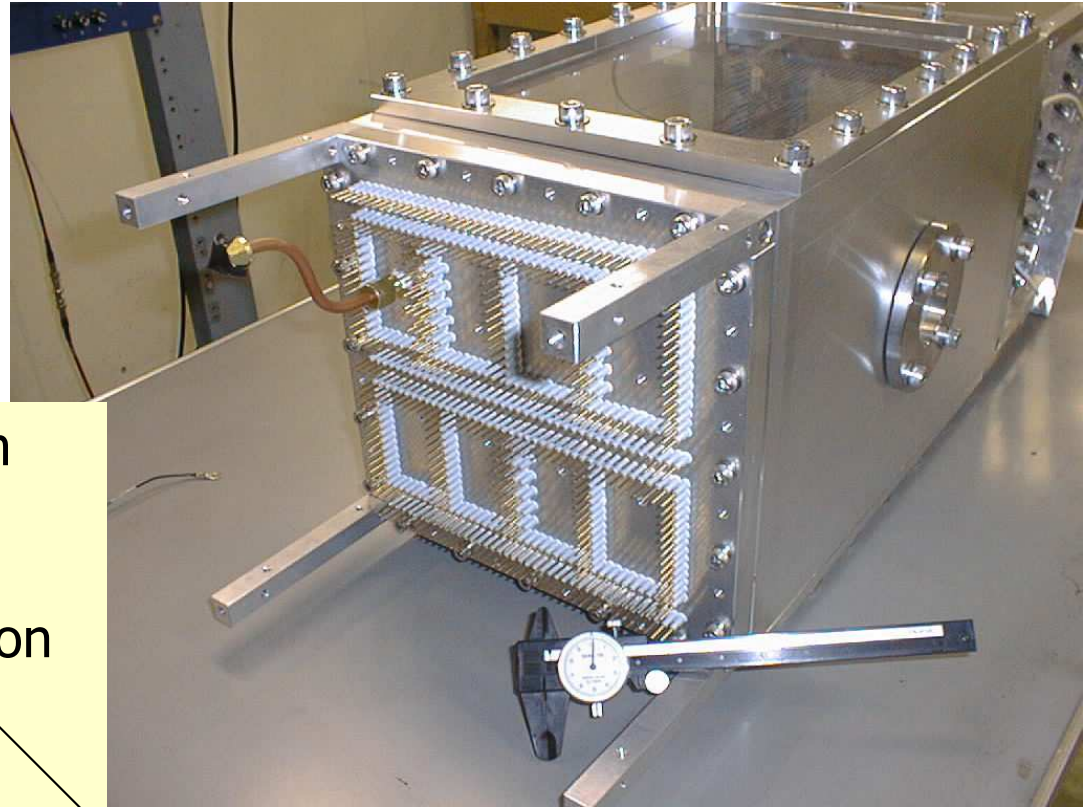
Wire sag, electromechanical instability

5 sense wires/cell, 1 cm height
 5 cm drift
 Note: triple field wire will reduce instability
 Wire positions measured with CCD cameras.
 Sense wire sag $\sim 100 \mu\text{m}$, field $100 \mu\text{m}$
 Motion with voltage on minimal,
 no instability observed

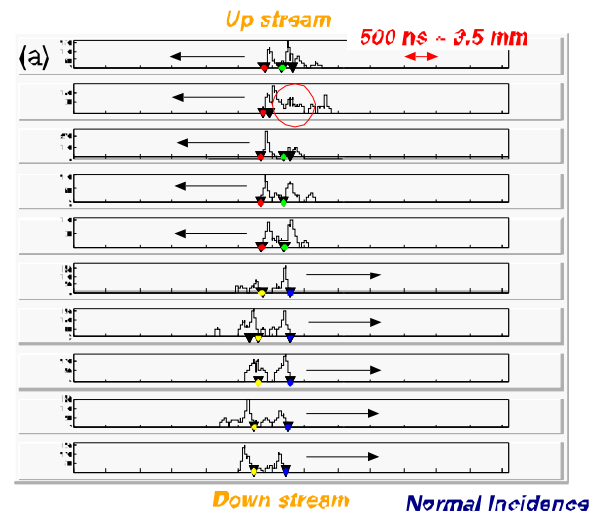
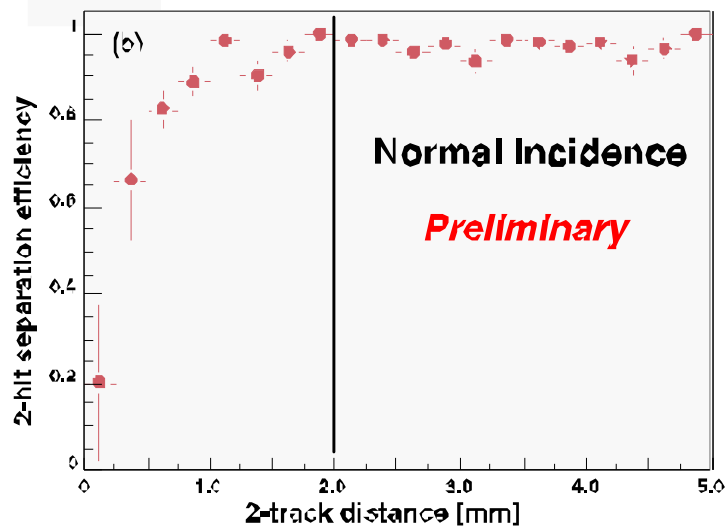


Stolen from JLC website, N. Khalatyan, Tsingua

Jet Chamber Track separation



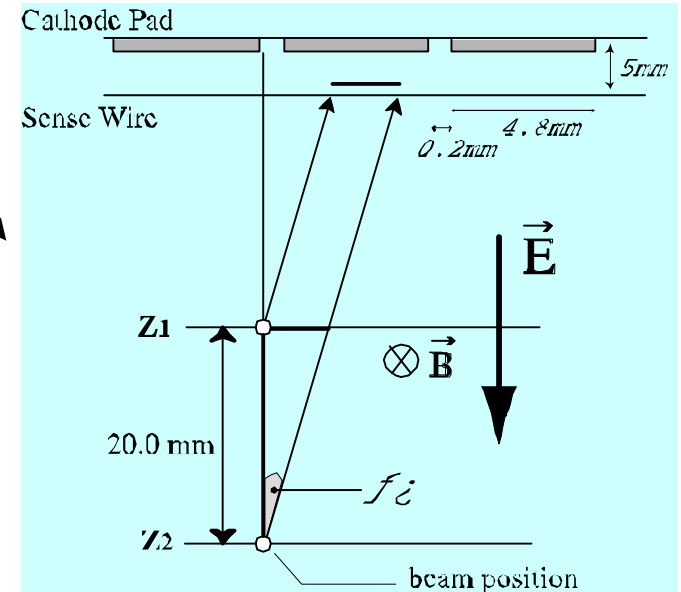
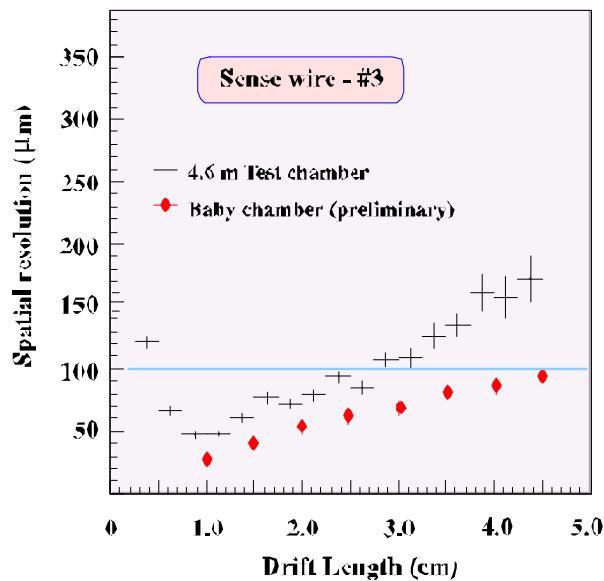
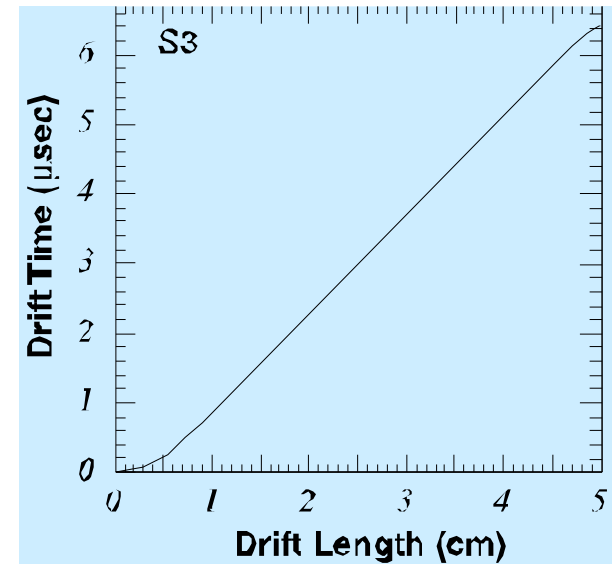
Small jet cell chamber in test beam
 e^+e^- pairs from conversions
 ADC signals analyzed for separation
 Observe 2 mm separation



Stolen from JLC website, K. Fujii, FermiLab 2000

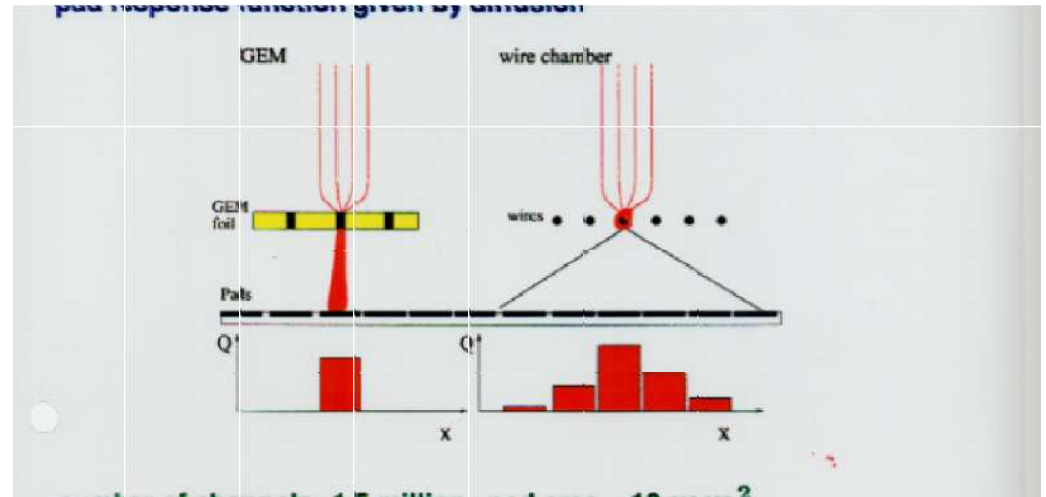
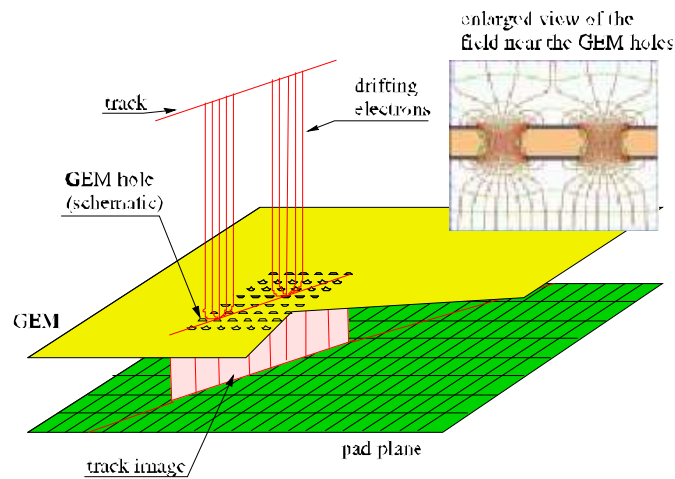
Jet Chamber Lorentz angle, Spatial Resolution

CO₂ – Isobutane (90/10)
 velocity $\approx 1 \mu\text{m/ns}$, (faster near wire)
 live time $\approx 1 \mu\text{s}$
 Lorentz angle $\approx 10^\circ$ at 2 Tesla, 19° at 1 Tesla
 Resolution 100 – 150 μm



Stolen from JLC website, N. Khalatyan, Tsingua

TPC with GEM or micro-GEM readout



Advantages electron collection, 100 μm spacing

Signal width is significantly reduced, improved segmentation

$E \times B$ effect (in radial part of electric field)

which limits resolution in an induction readout

is reduced with signal width

Problems

New technology

Signal width may be too small.

Must extract optimum resolution with finite of channels.

Gem TPC read-out
Stolen from TESLA TDR

Signal size in GEM and induction read-out

Stolen from M. Ronan, Vienna Conf. on Instrumentation , 22-Feb-2001

□ □ D, TP□ , G□□ □□ micro□ □ G□ □ read□o□t

Pad size □ narrow electron cloud ~ 1mm

requires 1mm pads to provide charge sharing, □ (10□) pads
wider pads (5mm□) will have poor resolution □ $w/(12)^{1/2}$

Pad shape □ methods of spreading signal to
limit channel count and improve resolution

chevrons □ ganging □ induction □

Beware, efforts to spread signal may compromise 2-track separation.

Aging □ GEMs can fail at high gain, relatively new technology,
dependence on gas choice

Gas □ diffusion, velocity

Active R&D

Aachen, Carleton/Montreal, DESY/Hamburg, Karlsruhe, Krakow,
LBNL, MIP-Munich, MP, NUSHE,
Novosibirsk, Orsay/Saclay, Purdue

GEM point resolution, Carleton

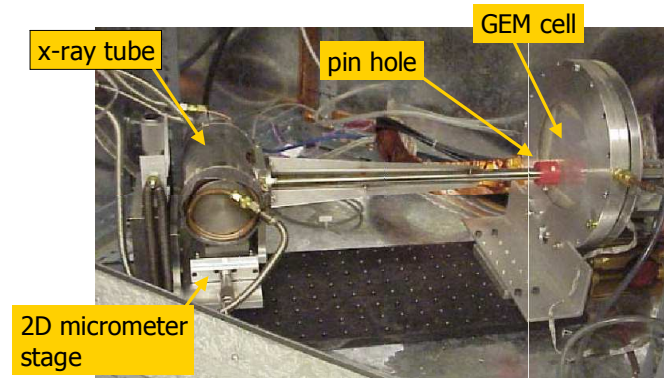
X-ray incident on indicated point.
(not a TPC)

Charge shared signal is observed on 3 pads (2.5 mm hex).

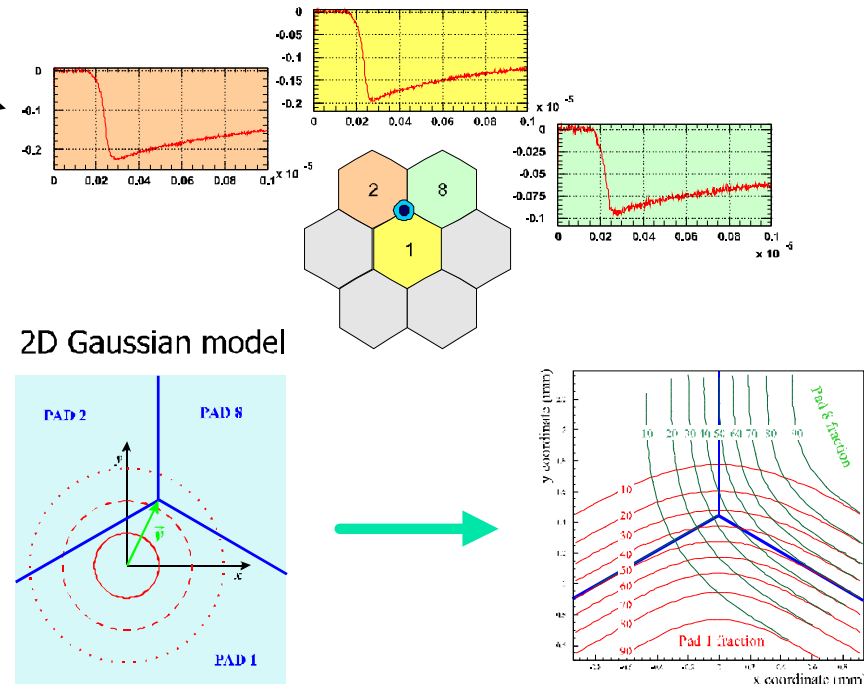
Direct charge collection signal has about 1 μ s width, 10 MHz

Charge sharing contours (lower right) indicate that signal width is 1 mm.

Spatial resolution is $\approx 100 \mu$ m, but only 1mm from boundaries.



Localization from charge sharing



8 January 2002

Dean Karlen / Carleton University

X-ray signal spatial resolution
Stolen from D. Karlen , Chicago Linear Collider Workshop, 7-Jan-2002

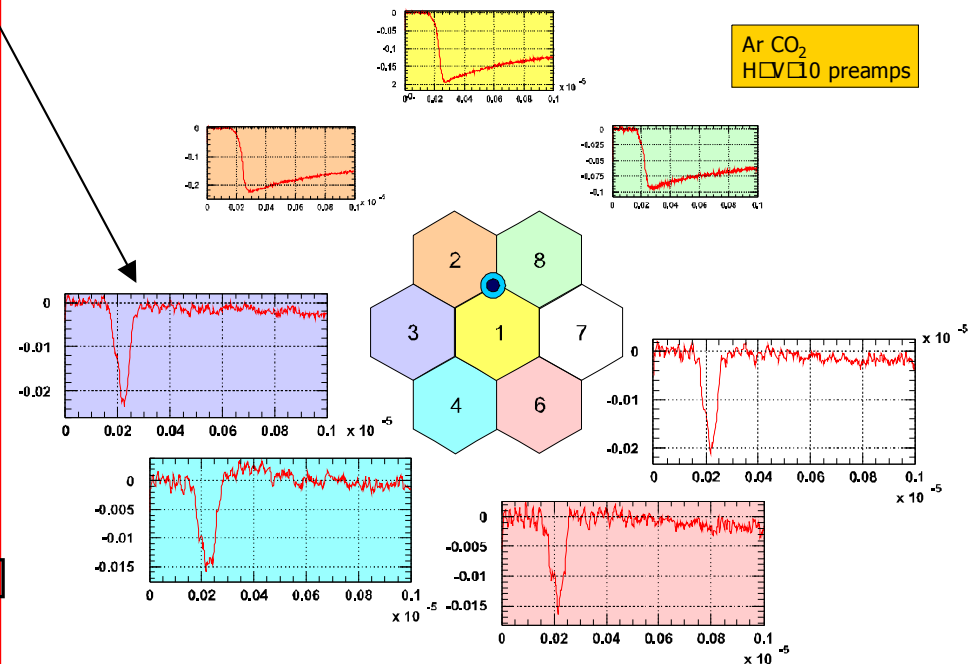
GeV point resolution induction, Darleton

Also measured **induction signals** on neighboring pads.
(same event)

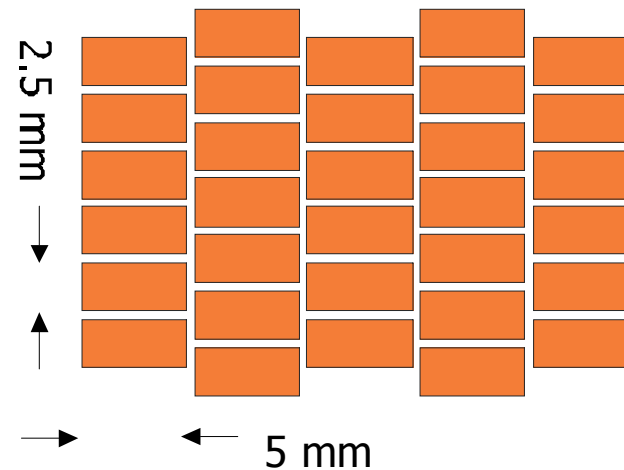
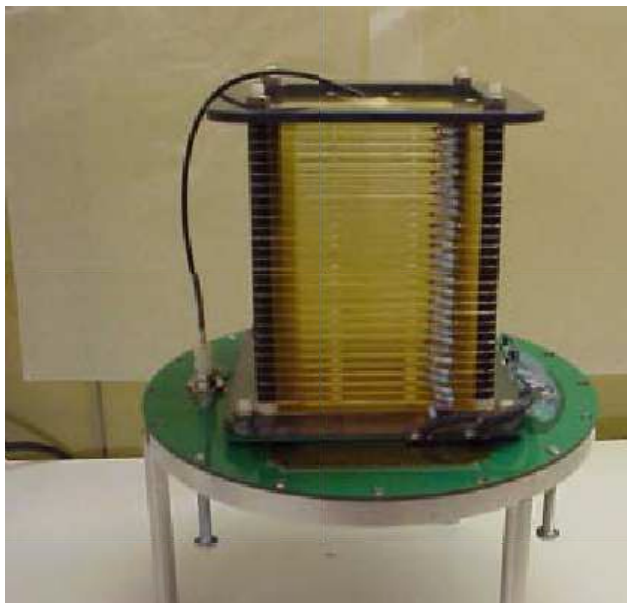
Spatial resolution is $\approx 100 \mu\text{m}$ and not dependent on 1 mm pad size.

Signal width (threshold-threshold) $0.1 \mu\text{s}$, **requires 50-100 MHz**

However, induction is **inconsistent with 2-track separation** could be used in isolated sections to improve resolution.



TPC with
 GEM
 readout,
 Carleton



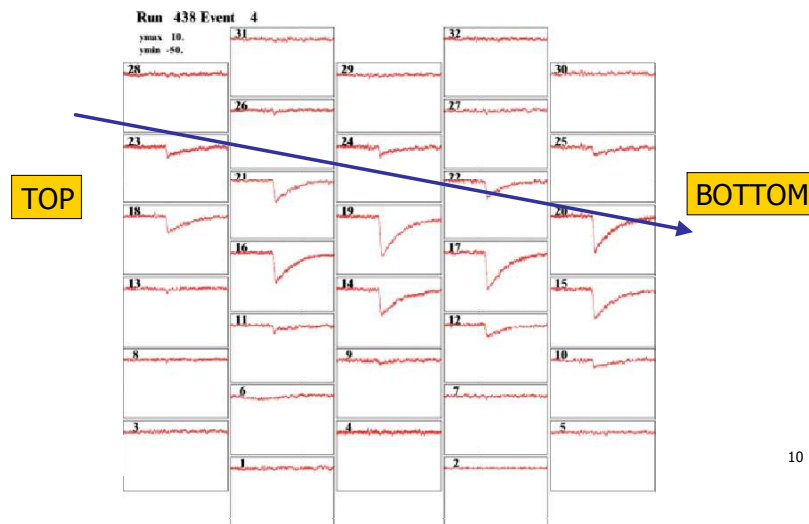
Resolution with P10 gas
 $220 \mu\text{m}$, 10 mm
 $500 \mu\text{m}$, 150 mm

Explanation large diffusion contribution
 (no magnetic field)

Extrapolates to $200 \mu\text{m}$ at 100

Questions

ion statistics (5 mm pad height)
 anomalous electron cloud size



Micro Pattern Detector Aging Radiation Hardness, Performance

Example triple GEM with PCB readout

Gas Ar/CO₂ 10/10 (99.99%)

GEM1 100 V

GEM2 90 V

GEM3 110 V

PCB as e⁻ collector

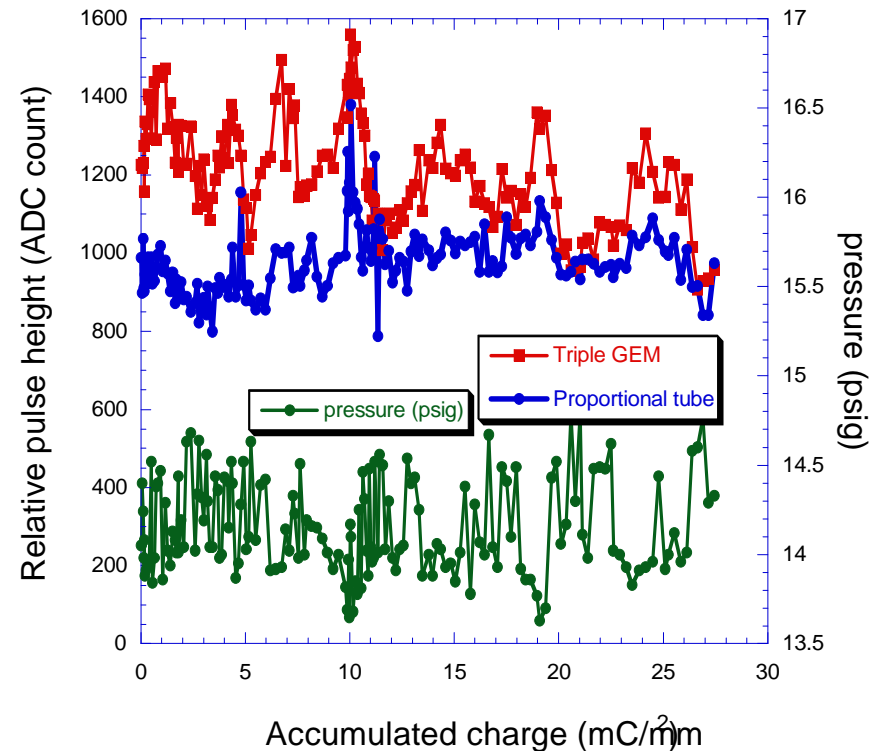
Cr rays (5.0 MeV)

1 x 10¹⁴ H/mm² for 50hrs

Gas gain 1000

Detector performance
small (~15% gain loss) after
~ 1 years LHC 10 cm from IP.
No visual sign of aging.

Best result obtained with a GEM.



Similar result obtained with
A MicroMEGAS + GEM

TPC, GEMs, microGEM read-out, cont.

Tests in high magnetic field → reduce transverse diffusion, surprises

Electronics → sampling rate, Aleph → 1 MHz

100 MHz → required for faster gas or induction from neighboring pads

Typical live time may be 50 μ s, store 1 ms exposure at TESLA .

Amplification → signal size, break-down limit, pad height, gas

Mechanical → mounting gas amplifiers, minimizing inactive regions
high speed sampling may require cooling

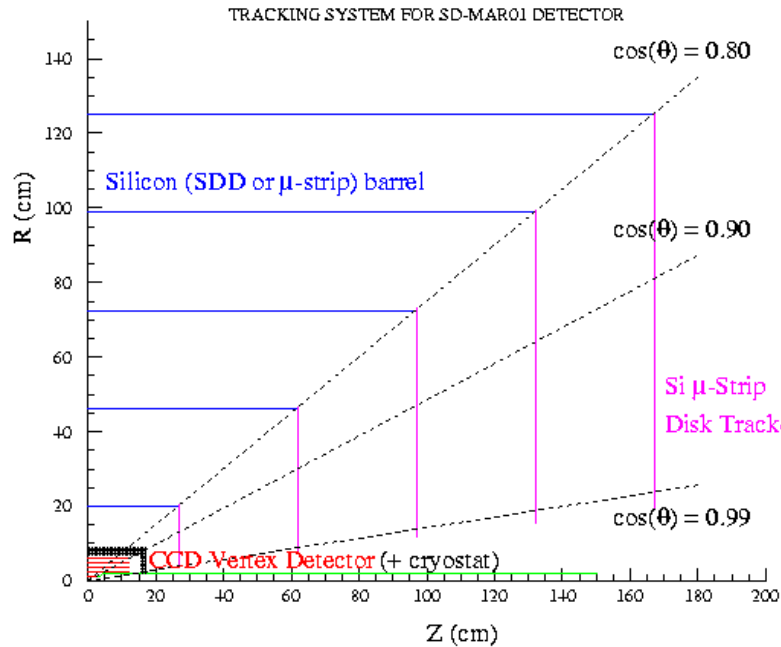
(and, as in induction read-out TPC)

On feed-back → multi-GEMs or MicroMEGAS (appears better)
and/or gating grid

Gas → quenching with hydrocarbons vs neutron cross section

Alignment methods → internal, external, consistent with improved resolution
(and, in an inhomogeneous magnetic field)

Silicon Tracking



Provides improved segmentation
 $\delta(1/P_t)$ in a small package
 Disadvantages
 pattern recognition issues
 material issues (low momentum)
 limited dE/dx

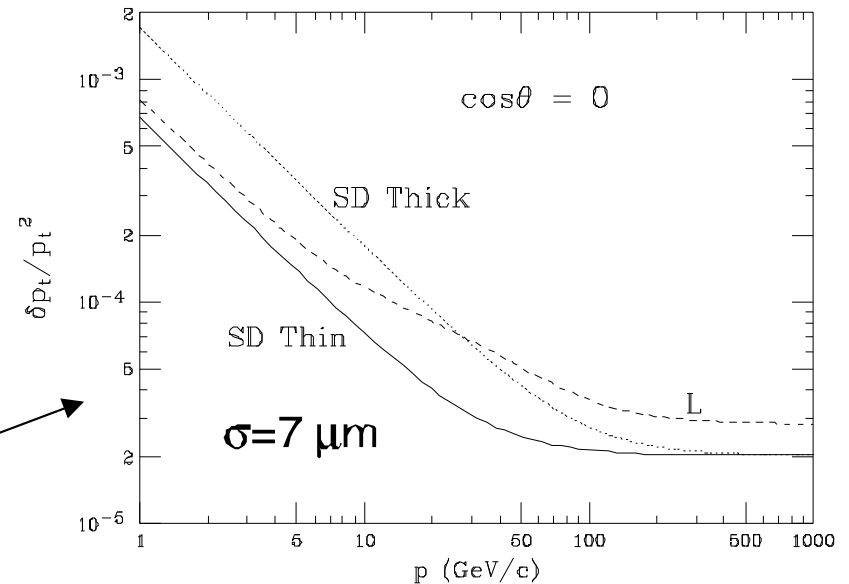
2 technologies being pursued by
 North American groups
 Silicon μ -strip
 Silicon Drift

$$\delta(1/P_t) \approx \frac{\sigma/L^2 \left(\frac{20}{(N+1)} \right)^{.5}}{(. \text{GeV/Tesla } B)}$$

With $L = 1.25$ m, $B = 5$ Tesla,

$\sigma = 10$ μ m, $N = 1$

$$\delta(1/p) \approx 1.5 \times 10^{-5} / \text{GeV}$$



Stolen from B Schumm, SILC phone/web meeting, 4-Apr-2002

□ □ D , all silicon tracking

Organizational meeting □ April □ Bruce Schumm, UCSC

Silicon μ -strip □ R&D, UC Santa Cruz

reduce material, detectors must be very thin, 200 μm + no support

(CLEO □ 100 μm plus support)

to compete with budget of TPC (1. □ □ □ in inner support)

long shaping time, allows ultra low noise for thin detectors, 10 μs

(CLEO □ 1 μs)

minimal support material, possibly tensioned

power cycling, reduce heat load, can this be done without adding noise □

resolution, 50 μm pitch with centroid finding for required □ μm

Silicon Drift □ R&D, Wayne State (next page)

Silicon Drift Detector

Electron drift in silicon,
 $r-\phi$ from pad, Δz from drift time
Maximum drift $\leq 5 \mu\text{s}$

Mature technology, STAR vertex detector

LC Central tracker
Five layers

Goals

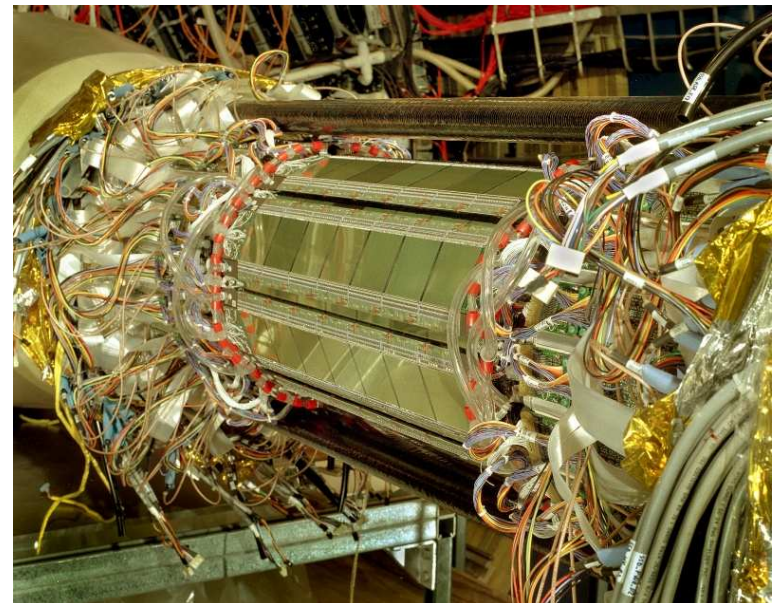
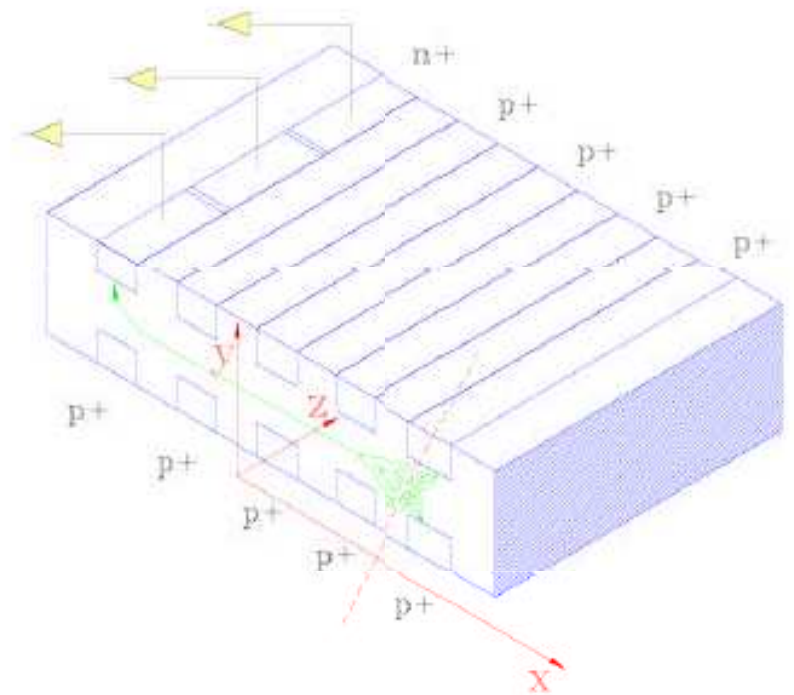
Radiation length / layer ≤ 0.5

$\sigma(r-\phi) \leq 10 \mu\text{m}$, $\sigma(\Delta z) \leq 10 \mu\text{m}$

Wafer size $10 \text{ cm} \times 10 \text{ cm}$

Wafers 1000 (incl. spares)

Channels 100×100 ($200 \mu\text{m}$ pitch)



□ □ D , silicon drift detector

Ongoing/planned at Wayne State

□ Improve radiation length, STAR is 1.□□ per layer

Reduce wafer thickness from □□ to 150μm

Move □EE to edges or change from hybrid to SV□

Air cooling vs. water cooling

More extensive radiation damage studies.

Detectors/□EE can withstand around 100 krad (γ, n)

□ Improve position resolution to 5μm

Decrease anode pitch from 250 to 100μm.

Stiffen resistor chain and drift faster.

PASA is BIPOLAR (intrinsically rad. hard.)

SCA can be produced in rad. hard process

Intermediate tracker, Forward Disks

Motivation □ Improve momentum resolution
extend efficiency to $\cos(\theta) \approx 995$

Technology □ spatial resolution goal requires silicon technology
pixel devices
or the silicon devices proposed for all silicon tracking

Performance Issues □ many tracking studies to
optimize performance and prove effectiveness (below)

Mechanical Issues □ solve mounting problems.
Structures must be **rigid and aligned to the central tracker**,
(note □ degraded resolution for 25 μm misalignment)
yet **independent of central tracker** (for access).

□ □ D , physics motivation

Physics motivation studies will require a FAST Monte Carlo.

Momentum resolution □ realistic requirements (point of diminishing returns) for Higgs recoil mass and slepton endpoint spectrum, taking **into account other width contributions** □ particle decay widths, initial state radiation, beam energy spread.

Material budget □ realistic requirements, compelling physics example that determines the material limit, What $\delta p/p$ is required at 1 GeV/c □ What photon conversion rate is unacceptable □

dE/dx □ Compelling physics example where dE/dx make a difference.

□ □ D , system performance □ pat. rec. □

System performance studies will require a full Monte Carlo, including alignment errors, efficiency, detector response function, noise from multiple bunches, backslash, beam

Performance enhancers □

intermediate silicon tracking layer □

how much does this help for pat. rec. , $\delta p/p$ □

intermediate scintillating fiber layer (timing, bunch tagging)

outer □ layer (extrapolation into calorimeter)

outer end-cap tracker ($\delta p/p$ at low θ)

Performance in very high noise environment □ (higher than expected 1 □)

Performance with large electric field distortion (TPC) due to space charge

(although GEM/MicroMEGAS proponents confident that ion feedback

will be suppressed, maybe with gating grid

and primary ionization is claimed sufficient for expected accelerator backgrounds)

Wire saturation □ (in a drift chamber) from larger than expected

accelerator backgrounds, degrades time resolution, efficiency

□ □ D , pattern recognition issues

requires ALL Monte Carlo as on previous slide.

Mature pattern recognition that performs in high density environment

(which might include)

Non-linear methods allowing for global determination of the ambiguity arising from different matching of high-quality track-segments

Energy low Performance

realistic comparison of **track separation** performance

1D and 2D, silicon and gas options

TPC with induction vs GEM/MicroMEGAS, GEM with induction
evaluate (charge spreading) pad design for track separation

Silicon tracking demonstrated stand-alone track reconstruction,

□ for all silicon tracking options

including reconstruction of **decays in flight**

(fewer, more precise, hits vs continuum of less precise hits)

□ for silicon forward discs

□ for vertex detector, including self contained tracking seeds
successfully extrapolated into the outer tracker

R & D opportunities in Tracking

TPC

Spatial resolution optimization, goal of 150 μm in a large induction TPC.

On feedback suppression gating grids (long gate time at TESLA)

Gas studies aging, velocity (clearing time), quenching, neutron absorption

Alignment internal alignment and drift path in an inhomogeneous B field
extrapolation to an intermediate tracker hardware & tracking.

Optimize pattern recognition in an environment of **significant track overlap**.

Advanced readout TPC

Pad size narrow electron cloud $\sim 1\text{mm}$

requires 1mm pads to provide charge sharing, (10⁴) pads wider pads (5mm) will have poor resolution $\propto w/(12)^{1/2}$

Pad shape methods of spreading signal to limit channel count and improve resolution chevrons ganging induction

Amplification signal size, break-down limit, pad height, gas

Gas further studies diffusion

Tests in high magnetic field reduce transverse diffusion, surprises

Electronics sampling rate, Aleph 1 MHz 100 MHz required for faster gas or induction from neighboring pads

Typical live time may be 50 μs , store 1 ms exposure at TESLA .

Aging GEMs can fail at high gain, relatively new technology, dependence on gas choice

Mechanical mounting gas amplifiers, minimizing inactive regions high speed sampling may require cooling

Silicon μ -strip tracker

reduce material, detectors must be very thin, 200 μm + no support to compete with budget of TPC (1.0% in inner support)

long shaping time, allows ultra low noise for thin detectors, 10 μs

minimal support material, possibly tensioned

power cycling, reduce heat load, can this be done without adding noise

resolution, 50 μm pitch with centroid finding for required $\sim 10\mu\text{m}$

Silicon drift

improve radiation length, STAR is 1.0% per layer, require 0.5%

radiation damage studies.

improve position resolution to 5 μm . Decrease anode pitch from 250 to 100 μm .

Simulations

Momentum resolution realistic requirements for Higgs recoil mass and slepton endpoint spectrum,

Material budget realistic requirements, compelling physics example that determines the material limit,

dE/dx compelling physics example where dE/dx make a difference.

Performance enhancers intermediate silicon tracking layer how much does this help for pat. rec. , $\delta p/p$

intermediate scintillating fiber layer (timing, bunch tagging)

outer layer (extrapolation into calorimeter)

outer end-cap tracker ($\delta p/p$ at low θ)

Performance in very high noise environment (higher than expected 1%)

Performance with large electric field distortion (TPC) due to space charge

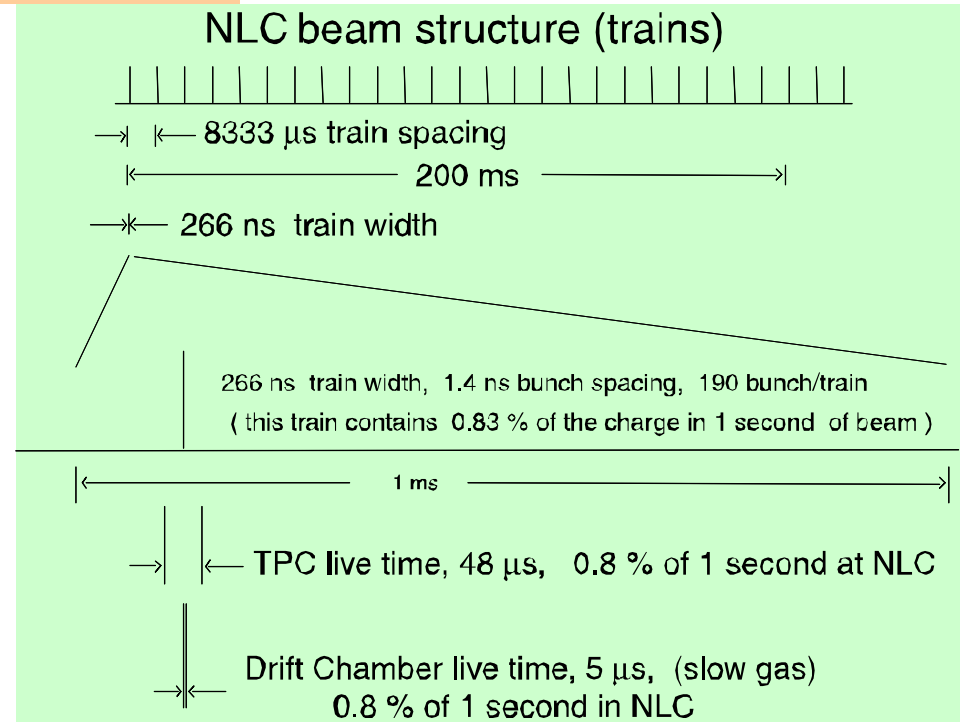
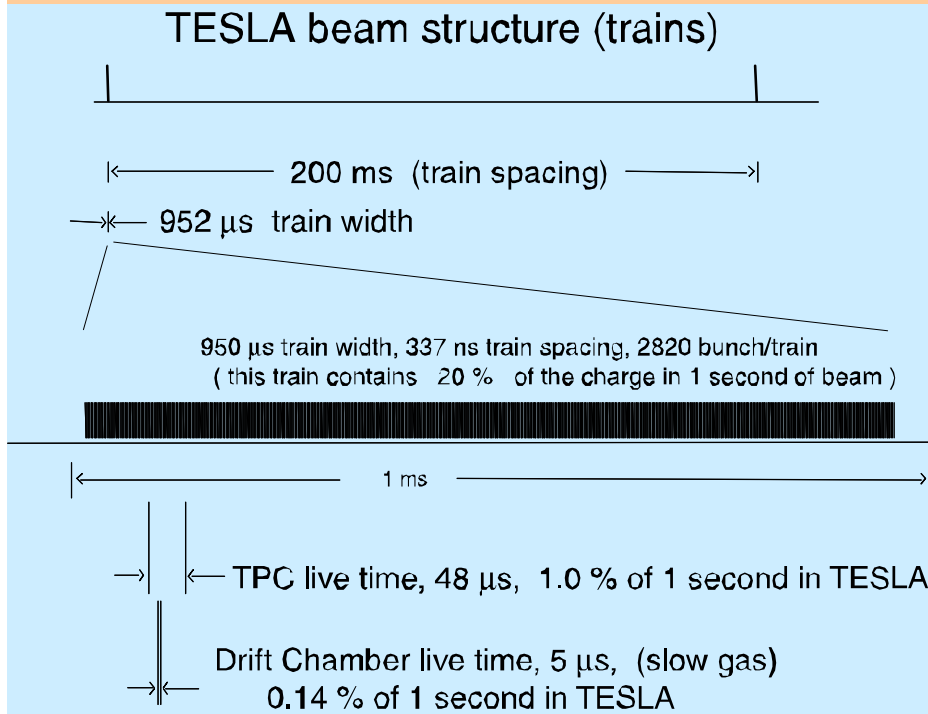
Wire saturation (in a drift chamber) from larger than expected accelerator backgrounds, degrades time resolution, efficiency

Mature pattern recognition that performs in high density environment

Energy flow Performance realistic comparison of **track separation** performance 1D and 2D, silicon and gas options

Silicon tracking stand-alone track reconstruction, for all silicon tracking options , silicon forward discs vertex detector

Beam Structure Issues



A TPC is not a trigger device.

Although the maximum drift is about 50 μ s, data collected throughout the entire train width (950 μ s at TESLA) must be stored in the electronics, 20,000 time buckets/channel at 20 MHz. Compress data during train.

A Drift Chamber is sensitive to the same amount of radiation (one train) as a TPC in NLC/JLC. TPC segmentation provide noise immunity.

However, a drift chamber would have reduced beam noise at TESLA.